

Challenges and possible solutions for inspection of field spot spraying robots

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SPISE Workshop, NL, May 2023



Outline

- Overview of technology used in Norway needing adapted inspection
- Kilter spot sprayer robot working system
- Solution for inspection of Kilter robot
- Third party equipment and inspection
- Discussion of solutions
- Briefly orientation about the new web-based inspection protocol system in Norway



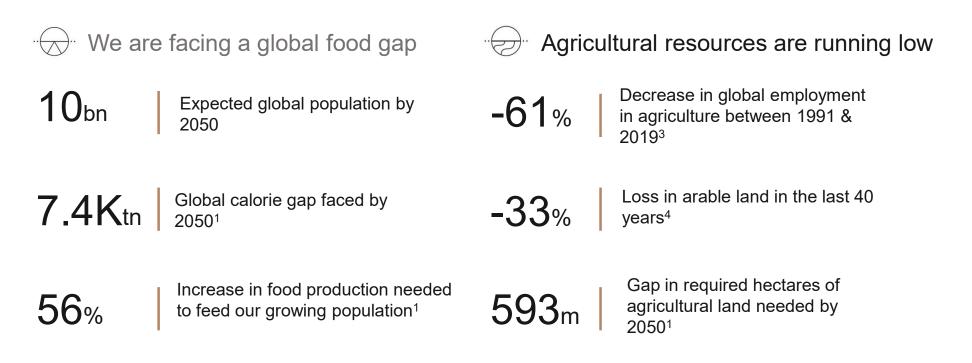
Kilter

"We're here to accelerate the restoration and rebalancing of the food and earth systems"

Kilter Systems in balance

Kilter AS, Berghagan 3, 1405 Langhus

Our global food system is under threat



Farmers globally are challenged to produce considerably **more and better food, with significantly less resources**

Sources: (1) World Resources Institute & FAO 2019, (2) WHO 2016 Estimates, (3) ILOSTAT 2021, (4) The University of Sheffield's Grantham Centre for Sustainable Futures

Kilter Systems in balance





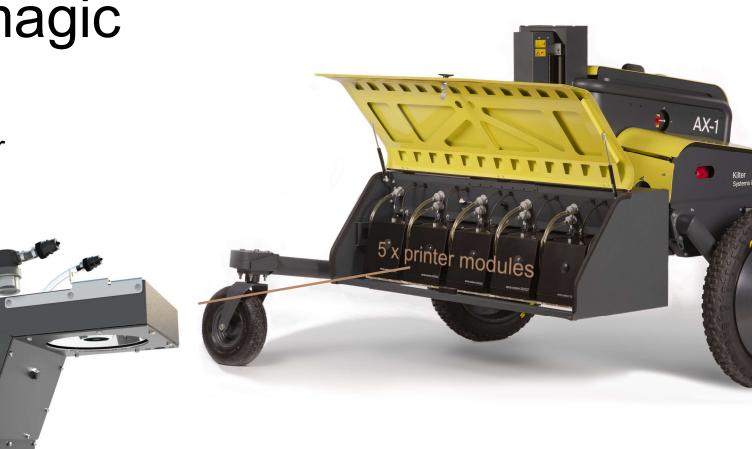
Problem

The vegetable fields of Europe are blanket sprayed with herbicides appx. four times pr season



Underlying magic

Artificial Intelligence Patented droplet generator Self-driving platform

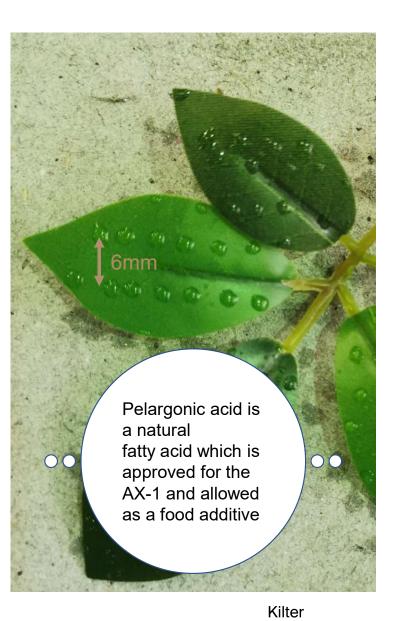


Kilter Systems in balance

AX-1 marks a paradigm shift

- Selectivity moved from chemistry to software (AI)
 - Precision allows early treatment
 - Patented droplet generator with revolutionizing spraying precision

Kilter's **tested**, **proven and patented** droplet technology drops a precise amount of herbicide onto weeds, **which allows for the use of bioherbicides** such as pelargonic acid without touching and killing the crop.



Systems in balance

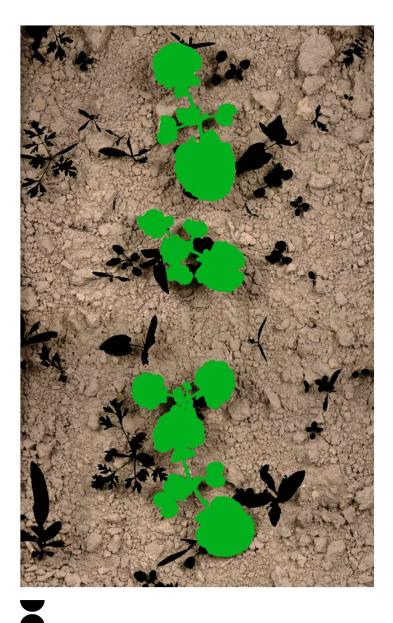


Emerging vegetable Nice timing for weed handling

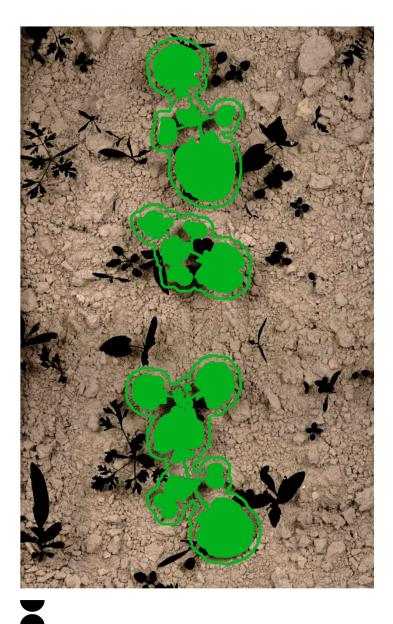




Emerging vegetable Nice timing for weed handling Conventional spraying

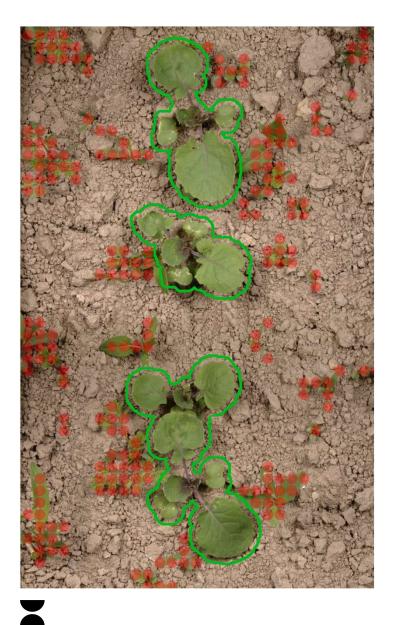


Emerging vegetable Nice timing for weed handling Conventional spraying With Kilter technology

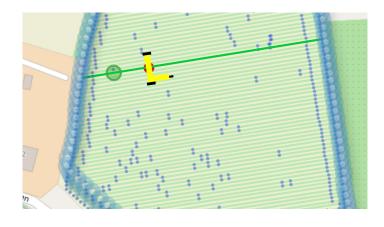


Emerging vegetable Nice timing for weed handling Conventional spraying With Kilter technology





Emerging vegetable Nice timing for weed handling Conventional spraying With Kilter technology





Self-driving

Autonomous operation

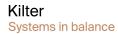
- RTK GNSS
 - IMU
 - Wheel sensors
- Predefined GNSS points
- Fault detection
 - Low on gas or herbicide
 - Geofencing (RTK GNSS)
 - Forward looking camera
 - Bumper sensor

Development and Production









Machinery directive

2006/42/EC EMC, 2014/30/E EN ISO 12100:2010 Agricultural

machinery

ISO 4254-1:2013 ISO 4254-6:2020 ISO 16119-1:2013 ISO 16119-2:2013 ISO 16122-2: 2015 ISO 3600:2015 Robots and robotic devices ISO 10218-1:2011

Nozzle design

ISO 5682-1:2017 ISO 25358:2018 And some more ISO 14982:1998 ISO 25119:2010 ISO 10625:2018 ISO 16236:2013 ISO 18497:2018 ISO 19732:2007 ISO 22368-3:2004 ISO 13850:2015 ISO 12100:2010 ISO 11684:1995 ISO 3767:2016

ISO 9357:1990

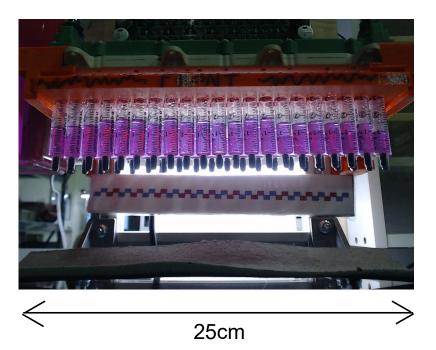
Regulations and conformity

- Engaged RISE SMP in 2019 to assist with the process of complying with EU regulations and directives.
 - Screening
 - Inspection report
 - Risk assessment
 - Implement means
 - Certification Report
 - CE marking

SIS/TK 224 - Lantbrukssprutor SIS/TK 228 - Lantbruksmaskiner







Function test

Volume distribution and droplet size

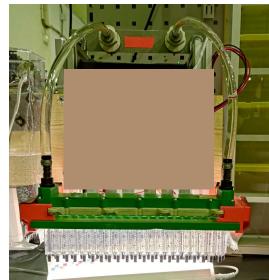
- Each nozzle shoots a known number (1000) of droplets to a container
- Randomly nozzle-shooting pattern
- Average droplet size per nozzle
- Distribution
- Automatic volume measurement through computer vision

Function test

Volume distribution



Conventional testing at JKI



High precision nozzles tested during production

Confidential, copyright Kilter AS



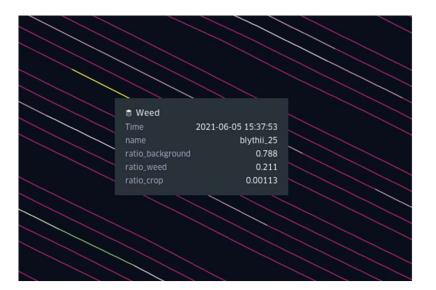
On-site function test

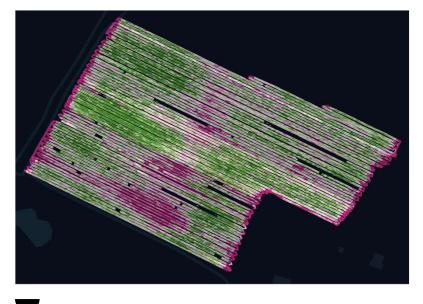


Function test

Self testing

- On robot
 - AX-1 detects and spray plastic plants or water sensitive paper
 - AX-1 takes pictures of the plastic plant or water sensitive paper and evaluates the results
 - AX-1 generates reports
- Tests Camera, mechanics and nozzles.





Reporting

cm level reporting

- Droplet distribution
- Crop distribution
 - And stages
- Weed distribution
 - And types of weed
- High detailed Images



To be discussed

- How to inspect spot sprayer robots;
 - -Important to control the working system
 - -Dependent of the equipment & robot
 - -Should be possible also for the farmer to execute calibration and control
- Solution
 - Involve the manufacturer to implement a tool or solution for inspection
 - -Autonomous and documented control if possible
- Start the work now in order to ensure adapted and proper solutions

Third-party solutions and inspection

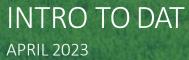


Patch spraying

A pragmatic and agronomic approach to precision spraying

Norwegian University of Life Sciences





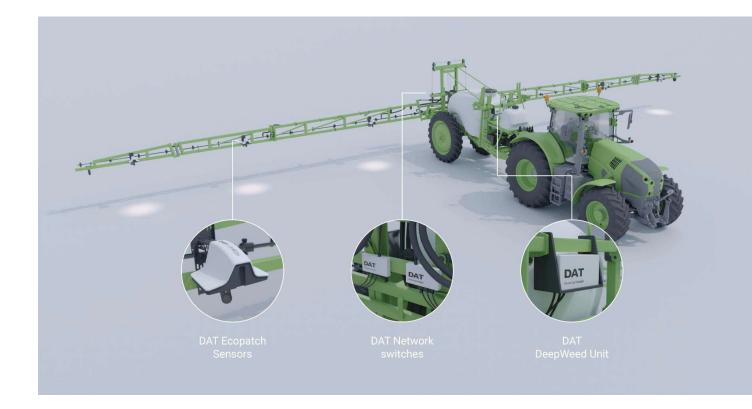
DAT ECOPATCH One Page Summary

- AI technology for patch spraying during growth season (green-on-green) in small cereal: Wheat, Barley, Oats, Rye
- Camera technology separates weeds from crop in real time and shut off sections where spraying is redundant
- Retrofit to all trailed and self-propelled sprayers (ISOBUS)
- Online to support OTA updates
- 2022-season: 40% herbicide reduction with DAT active
- Unsprayed areas experience increased yields (2-10%)
- Cover larger area before refill and hinders development of resistant weeds
- Weed heat map integrated to existing farm management platforms
- Developed and produced in Norway
- 2022: Commercial launch, 10 contracts (Norway + Germany)
- 2023: Actively approaching partners for commercialization and scaling
- Active systems in: Norway, Germany, Czech Republic, Lithuania and Spain





System overview – DAT EcoPatch



- 6-8 sensors mounted on exisiting spray boom taking high resultion images in real time
- Images are sent via switch boxes to processing in DAT DeepWeed Unit (ECU) which is connected via ISOBUS
- Sections are activated/deactivated based on signals sent from DAT DeepWeed Unit

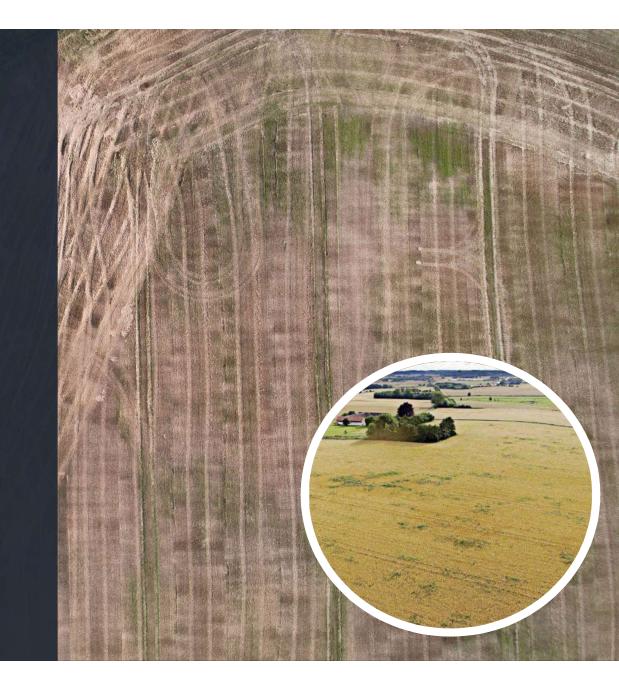


Patch spraying

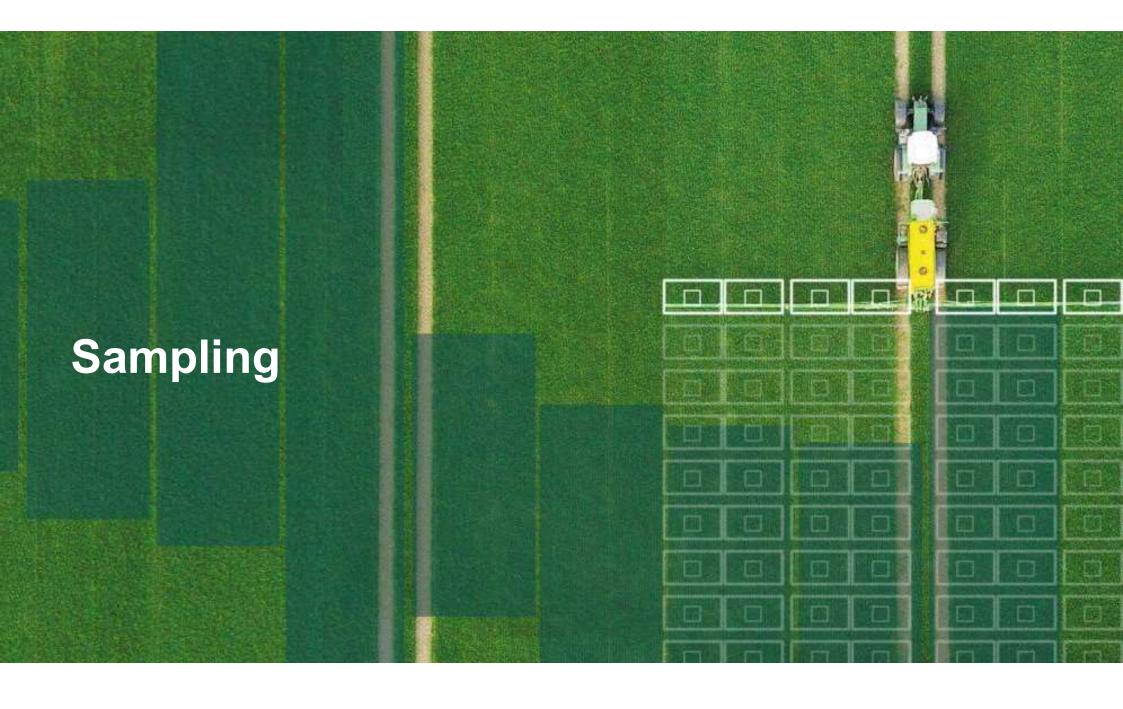
A pragmatic and agronomic approach to precision spraying

Weed Patches

- Research shows the spatial distribution of weed populations aggregates in patches.
- Result of the combination of the biological traits of the weed species and the inherent characteristics of the field like topography.
- In cereal fields patchy distribution has been shown for both monocots and dicots (grass and broadleaves)

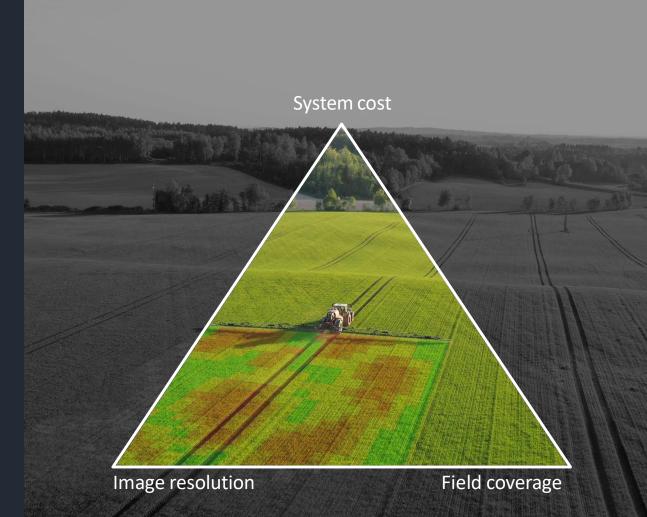






Why Sampling

- Optimization between image resolution, field coverage and system cost
- Enables the use of high resolution images to pick up small weed details
- Allows real-time spraying (i.e no extra work or drone piloting required)





4. June 2021 – Øvre Romerike

"Chess board effect"



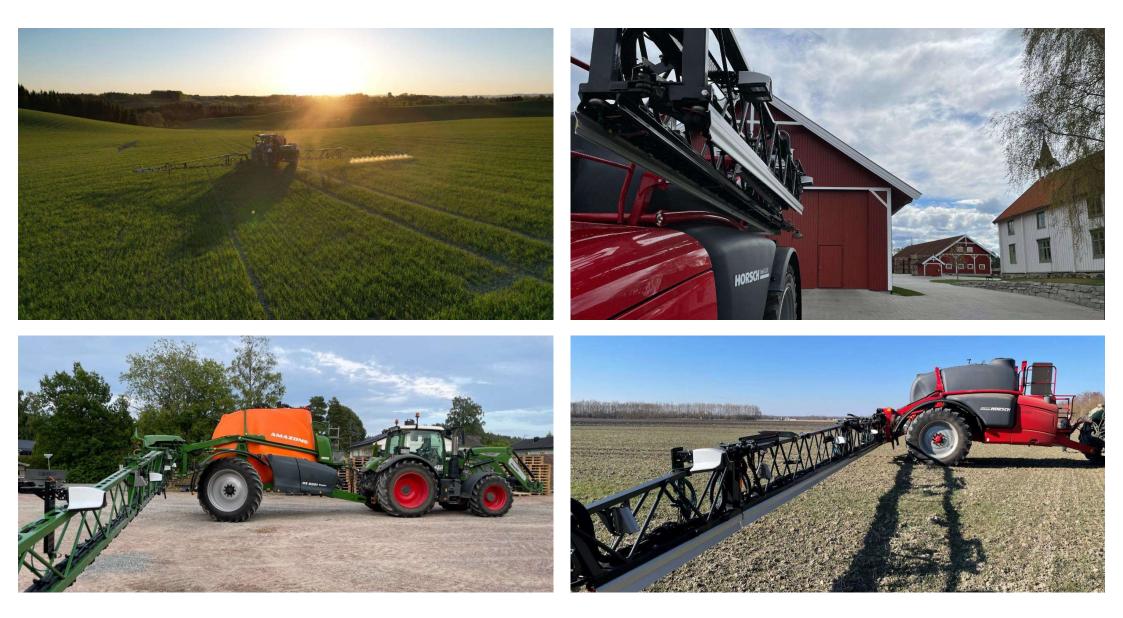
~2 week after spraying Dark green patches unsprayed and clearly healthier Explaining the increased yield?

Data collection

- A decade of data collection in multiple countries to train a robust, scalable machine learning algorithm
- Collected during spring and fall season
- Data added to the AI network daily
- Images are curated by skilled annotators and domain experts







Example: DAT Weed Heat Map uploaded to <u>Topcon Agriculture Platform (TAP)</u>



- Data from each sample point is related to a GPS coordinate and stored in CSV files
- The data is easily converted to shapefiles that can be uploaded to TAP (as seen on the left)
- The different data can be split into layers such as
 - Weighted relative weed cover (RWC)
 - Above / below threshold
 - As applied
 - Future opportunity to separate weed groupings such as monocot/dicot and specific weeds (*Tripleurospermum inodorum, Galium aparine, Poa annua and others*)
- Likely that DAT data can be uploaded directly via the TAP API





To be discussed

- How to inspect third party equipment;
 - -Important to control the working system
 - -Dependent of sensor technology and AI solutions
 - -Should be possible also for the farmer to execute calibration and control
 - -Could be challenging due to;
 - Responsibility between sprayer manufacturer and third party company
 - Inspector knowledge
 - Involvement of companies and level of costs

1. Sprøyten skal være ren Godkjent Reparert Avvist ₊	
2. Kraftoverføring og avskjerming - slitasje eller defekter	N
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3. Lekkasjetest (ved sprøytning)	Norwegian University of Life Sciences
Godkjent Reparert Avvist 🗮 🌀	

1. Krav til sprøyte FØR test Klikk her for å markere alle bokser med alternativet 'ikke relevant'.

4. Væskedusi og drypp på komponenter

1. Krav til sprøyte FØR test

34

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8. Vifte - intakt og fungerer	Norwegian University of Life Science
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Håling av manometer og/eller trykksensor

anometer	visning	Testresultat		Forskjell i trykk		Pumpekapa	isitet
1	bar	1	bar	0.00 bar	0.0 %	102	Vmin
1,5	bar	1,4	bar	-0.10 bar	-6.7 %	102	I/min
2	bar	2	bar	0.00 bar	0.0 %	101	l/min
3	bar	3,1	bar	0.10 bar	3.3 %		l/min
4	bar	4	bar	0.00 bar	0.0 %	I	l/min
5	bar	5	bar	0.00 bar	0.0 %	99	l/min
6	bar	6	bar	0.00 bar	0.0 %		l/min
8	bar	8,1	bar	0.10 bar	1.3 %	98	l/min
6	bar	6	bar	0.00 bar	0.0 %		l/min
4	bar	4	bar	0.00 bar	0.0 %		l/min
3	bar	3,1	bar	0.10 bar	3.3 %		l/min
2	bar	2	bar	0.00 bar	0.0 %		l/min
1,5	bar	1,4	bar	-0.10 bar	-6.7 %		l/min
1	bar	1	bar	0.00 bar	0.0 %		l/min



6. Betjening, målesystem og regulering

Klikk her for å markere alle bokser med alternativet 'ikke relevant'.

1. Manometer (trykkmåler) - lett lesbart, størrelse og skala

Godkjent	Reparert	Avvist	Ikke relevant	≣, @

2. Manometer (trykkmåler) - nøyaktighet og stabilitet

Godkjent

3. Reguleringsventiler og betjening

Godkjent

Godkjent

4. Trykkreguleringsventil

Ikke relevant Reparert Avvist

Avvist

Avvist

≣_ ⊘

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Ikke relevant

Ikke relevant

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Norwegian University of Life Sciences

INSPEKSJONSRAPPORT ÅKERSPRØYTE

Denne inspeksjonen er utført i henhold til ISO 16122-2:2015



Godkjent

Godkjent

INSPEKSJONSRAPPORT ÅKERSPRØYTE

Denne inspeksjonen er utført i henhold til ISO 16122-2:2015



Inspeksjon av firma -1000: Demonstration Company -,-,-, http://www.sonima.nl/ , norway@inspecting.online Funksjonstest

Funksjonstest dato 27-04-2023 ved Demo Account Frist for neste 27-04-2026 funksjonstest Resultat Godkjent etter reparasjoner Testprotokoli nr 1001

Kommentarer / forslag

Reparent kraftuttaksaksel

A			

Akersprøyte				
Serienummer	00111	Pumpekapasitet	100 / min	
Fabrikat	Hardi	Pumpetrykk	15 bar	
Туре	NK800	Omrøring	Hydraulisk	
Produksjonsår	1999	Sprøytebom: Arbeidsbredde	10 meter	
Sprøytetype	3pkt montert	Sprøytebom: Antall seksjoner	1	
Kategori	Akersprøyte	Avstand mellom dyser	50 cm	
Tankkapasitet	BDD liter	Antall dyser	20	
Pumpe: Fabrikat	Hardi	Max. capacity of 1 nozzle	2.31/min	
Pumpetype	Stempel / Membran			

Eier

Kunde-ID

Adresse

Navn

Kaptein Krok

Kaptein Krok

krokvelen, 1722, Sarpsborg, Norge

1 Krav til sprøyte FØR test

2	Kraftoverføring og avskjørming - slitasje eller defekter	Godkjent
2	Se bilde 1	

3 Væskepumpe

- 19	Pumpekapasht
-	Min. omrøring: 40.01/min
	Pumpekapasitet nedvendig for dyser: 46.01/ min
	Målt pumpekapasitet: 981/min
	Tilgjengelig kapasitet for omrering: 52.01/ min
	Maks kapasitet for 1 dyse: 2.64

Måling av manometer ogjeller trykksensor

Manameter cleaning (bar)	.1#	1.00	1.00	1.00	4.01	4.85	100	8.00	8.00	4.00	346	3.05	1.64	1.33
Testesullet (ker)	1.120	1.40	2.00	3.10	4.01	6.00	4.00	833	100	4.00	1.10	2.05	1.40	1.2
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Pumpehapastel (MAC)	102	100	1.101		- 8	80		80	_		_			

12 Dyser og væskefordeling

5	Trykktap - Bruk	kontrolidyse	e ved maling av trykkta	ap .
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Hvis dysekapasiteten er målt	2.00 bar	lik 1.20 liter/min og dyse
Så er trykket ved dyse ut på bomme	en ved 1.15 liter/n	nin lik 1.84 bar
Trykktap i prosent		B.16 %
Trykktap I bar		0.16 bar

Utstyr som brukes til måling av dysekapasitet: Sylindre/målebegre

Testresultat dyser - bruk av Lunmark fordelerbord

Hardi, ISO F-, 110 / 03 , Testhayde 40 cm , Testhykk 2 bar

Resultat: Godicient

		3					·			+0		14				18.	17	:10	
Testines/Itel	1,80	132	1.01	1.82	130	180	1.00	1.00	1:00	1.80	1.00	1.00	1.08	1.00	1.20	1=	1.00	1.60	180
Arrest feat arrited	0.00 (res)	0.00 (Real	0.0031040	0.02219941	O DE Data	600 mm	-0.221/wei	\$123 (Hile)	3.011000	G. BDI (Hear)	0.00.7em	0.08 (line)	8.00 time	0.00 (mm)	0.00 (0.001 (Arial)	4.03.000	10003984	0.00 (1996)
Arrow for some	3.0%	10%	34%	10%	2.1/12	345	0.0%	.08%	- 2.2.2	60%	111	12%	0.0%	34%	. 60%	10%	100%	- 80.%	8.015

Signatur av: Demb Account

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Thank you for your attention!

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